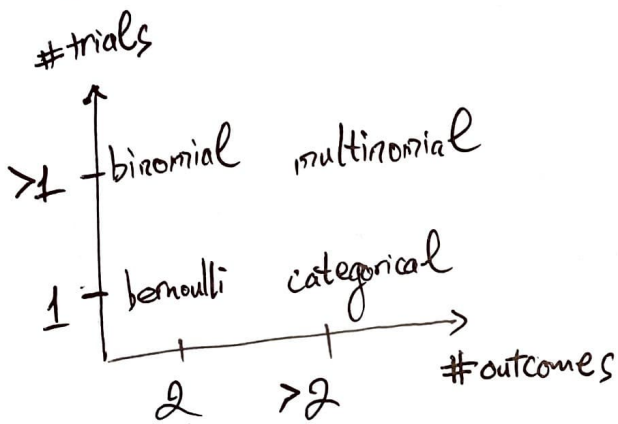


# Distributions

## Discrete



Poisson:  $P(k) = \frac{\lambda^k e^{-\lambda}}{k!}$

## Continuous

Gaussian:

$$P(x) = \frac{1}{\sigma \sqrt{2\pi}} e^{-\frac{1}{2} \left(\frac{x-\mu}{\sigma}\right)^2}$$

Beta :  $P(x) = \frac{x^{\alpha-1} (1-x)^{\beta-1}}{B(\alpha, \beta)}$

# Linear Regression

Solution:

$$w_1 = \frac{m \sum_{i=1}^m x_i y_i - \sum_{i=1}^m x_i \sum_{i=1}^m y_i}{m \sum_{i=1}^m x_i^2 - \left(\sum_{i=1}^m x_i\right)^2}$$

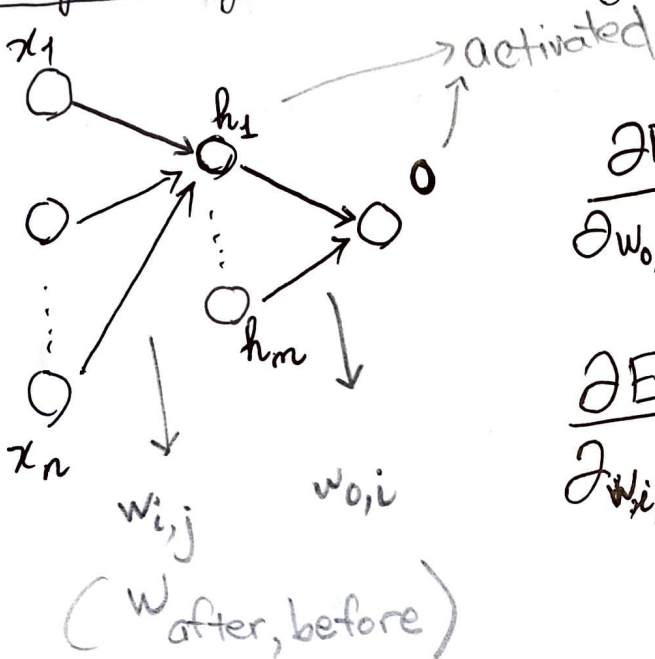
(Univariate)

$$w_0 = \frac{1}{m} \left( \sum_{i=1}^m y_i - w_1 \sum_{i=1}^m x_i \right)$$

(Multivariate)  $\vec{w} = (X^T X)^{-1} X^T Y$

Neural net

2-layer's algo: GD w/ following update rules



$$\frac{\partial E}{\partial w_{o,i}} = -2(y-o)o(1-o)h_i$$

$$\frac{\partial E}{\partial w_{i,j}} = -2(y-o)o(1-o)w_{o,i} \times h_i(1-h_i)x_j$$

Dynamic programming:

Forward

$$h_i = a\left(\sum_{j=1}^n w_{i,j} x_j\right)$$

$$o = a\left(\sum_{i=1}^m w_{o,i} h_i\right)$$

Backward

$$\delta_i = \delta_o h_i(1-h_i)w_{o,i}$$

$$(w_{i,j} \pm \alpha \delta_i x_j)$$

$$\delta_o = (y-o)o(1-o)$$

$$(w_{o,i} \pm \alpha \delta_o h_i)$$

AND perceptron (old input)

$$w_i = \begin{cases} +1 & \text{if } X_i \text{ in Clause} \\ -1 & \text{otherwise} \end{cases}$$

$$w_0 = -k + 0.5$$

$$\text{Clause} = X_1 \wedge \dots \wedge X_k \wedge \bar{X}_{k+1} \wedge \dots \wedge \bar{X}_n$$

OR perceptron

same

$$w_0 = n - 1/2 - k$$

## Bias & Variance

$$\begin{aligned}
 \mathbb{E}[(y^* - h(x^*))^2] &= \mathbb{E}[(h(x^*) - \mathbb{E}[h(x^*)])^2] \xrightarrow{\text{var.}} \\
 &+ (\mathbb{E}[h(x^*)] - f(x^*))^2 \xrightarrow{\text{Bias}^2} \\
 &+ \mathbb{E}(\epsilon^2) \xrightarrow{\text{noise}}
 \end{aligned}$$

### Bias

Low:

- Linear Reg on linear data
- 2<sup>nd</sup> polynomial on quadratic data
- NN with many hidden units trained to completion

High - const

- Linear Reg on non-linear data
- NN with few hidden units on non-linear data

### Variance

Low - const

- model  $\perp$  training data

High:

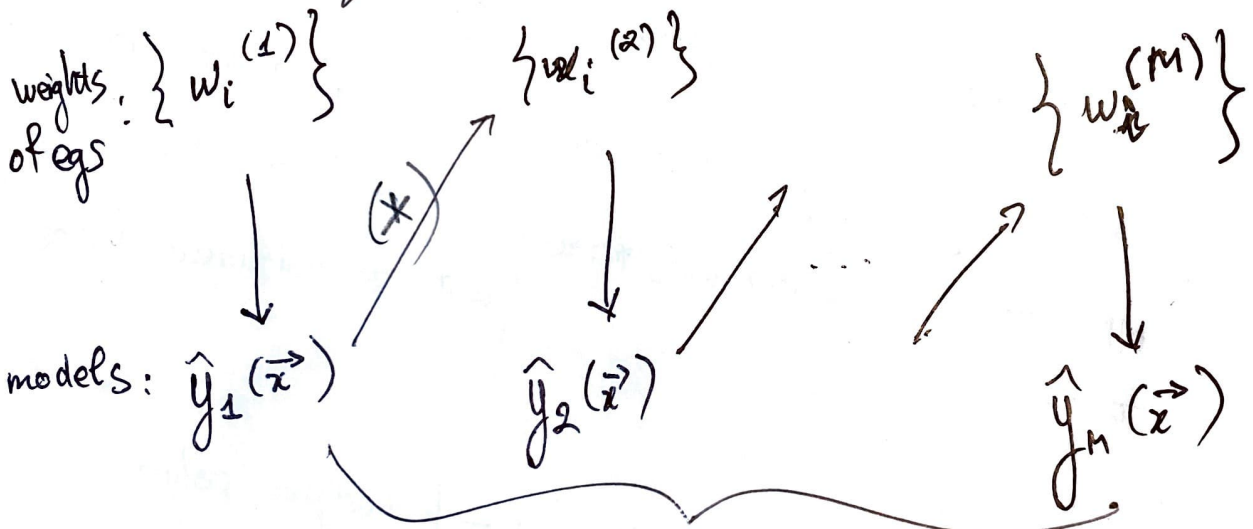
- high degree polynomial
- NN w/ many hid. units (complete training)

# Ensembles

- Bagging: trained  $K$  models, each on one "bootstrap"  
(bootstrap: same-sized dataset by sampling WITH replacement)

$\Rightarrow$  Only help UNSTABLE learners (NN, DT)  
(not KNN, NB)

## ~~Ada~~ Boosting



$$Y(\vec{x}) = \text{sgn}\left(\sum_{i=1}^M \alpha_m \hat{y}_m(\vec{x}_i)\right)$$

In AdaBoost:

$$\text{Error}_m = \frac{\sum_i w_i \times \mathbb{I}(y_i \neq \hat{y}_m(\vec{x}_i))}{\sum_i w_i}$$

$$(**): \alpha_m = \log\left(\frac{1 - \text{Error}_m}{\text{Error}_m}\right)$$

$$(*) = w_i * = e^{\alpha_m \times \mathbb{I}(y_i \neq \hat{y}_m(\vec{x}_i))}$$